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Model Choice and Variable Selection for Discrete Valued Data Using an Auxiliary Mixture Sampler

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joint work with

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Outline

- Auxiliary mixture sampler for Bayesian modelling of discrete-valued data
- Model choice for state space models for discrete-valued data
- Variable selection for regression models for discrete-valued data
- Covariance selection in random-effect models for discrete-valued data

Binary logit model

$$\Pr(y_i = 1 | \beta) = \frac{\exp(\mathbf{x}_i \beta)}{1 + \exp(\mathbf{x}_i \beta)},$$

$y_i = 1/0$. . . buy/not buy a product

\mathbf{x}_i . . . product attributes (brand, price)

β . . . part worths

Bayesian Analysis

The presence of the logit transformation causes **non-normality** as well as **non-linearity** \Rightarrow Metropolis-Hastings algorithm

A Gibbs sampling algorithm could be applied, if the model were **normal** and **linear**, in particular for a standard regression model:

$$y_i^u = \mathbf{x}_i \boldsymbol{\beta} + \varepsilon_i, \quad \varepsilon_i \sim \mathcal{N}(0, \sigma_\varepsilon^2).$$

Recalling the Concept of Utility (McFadden 1974)

Let y_{0i}^u be the utility of choosing category 0 (not buy).

Let y_i^u be the utility of consumer i to choose category 1 (buy).

Utility of buying is influenced by product attributes:

$$y_i^u = \mathbf{x}_i\boldsymbol{\beta} + \varepsilon_i.$$

If $y_i^u > y_{0i}^u \Rightarrow$ consumer will buy \Rightarrow observe $y_i = 1$

If $y_i^u < y_{0i}^u \Rightarrow$ consumer will not buy \Rightarrow observe $y_i = 0$

Recalling the Concept of Utility (McFadden 1974)

If y_{0i}^u and ε_i follow a type I extreme value distribution, then the marginal distribution of y_i corresponds to the binary logit regression model:

$$\Pr(y_i = 1 | \boldsymbol{\beta}) = \frac{\exp(\mathbf{x}_i \boldsymbol{\beta})}{1 + \exp(\mathbf{x}_i \boldsymbol{\beta})},$$

Data Augmentation - Step I (Scott 2004)

Estimate the latent utilities of category 1 jointly with β using a two step MCMC algorithm

1. Sample β conditional on $\mathbf{y}^u = (y_1^u, \dots, y_N^u)$ from the model

$$y_i^u = \mathbf{x}_i \beta + \varepsilon_i. \quad (1)$$

2. Recover the latent utilities $\mathbf{y}^u = (y_1^u, \dots, y_N^u)$ knowing β

Model (1) is a linear regression model with non-normal error term $\varepsilon_i \Rightarrow$ Scott (2004) uses Metropolis-Hastings to sample β

Recovering the Latent Utilities

Very efficient sampling step:

Sample the latent utility y_i^u conditional on β and \mathbf{y} as

$$y_i^u = -\log \left(-\frac{\log(U_i)}{1 + \lambda_i} - \frac{\log(V_i)}{\lambda_i} I_{\{y_i=0\}} \right),$$

where U_i and V_i are two independent uniform random numbers and $\lambda_i = \exp(\mathbf{x}_i\beta)$.

A single line of code in MATLAB or in R!

Proof requires just a bit of probability theory

Achieving Normality

To obtain a model that is conditionally normal, approximate the non-normal density $p(\varepsilon_i)$ by a normal mixture of 10 components with parameters m_r and s_r for the r -th component:

$$p(\varepsilon_i) = \exp\{-\varepsilon_i - e^{-\varepsilon_i}\} \approx \sum_{r=1}^{10} w_r f_{\mathcal{N}}(\varepsilon_i; m_r, s_r^2).$$

w_r	0.00551	0.0458	0.173	0.144	0.122	0.0989	0.102	0.114	0.106	0.0895
m_r	5.08	3.18	1.76	1.19	0.731	0.368	0.0279	- 0.314	- 0.677	- 1.06
s_r^2	3.58	1.73	0.975	0.379	0.178	0.096	0.0703	0.0705	0.0896	0.145

Achieving Normality

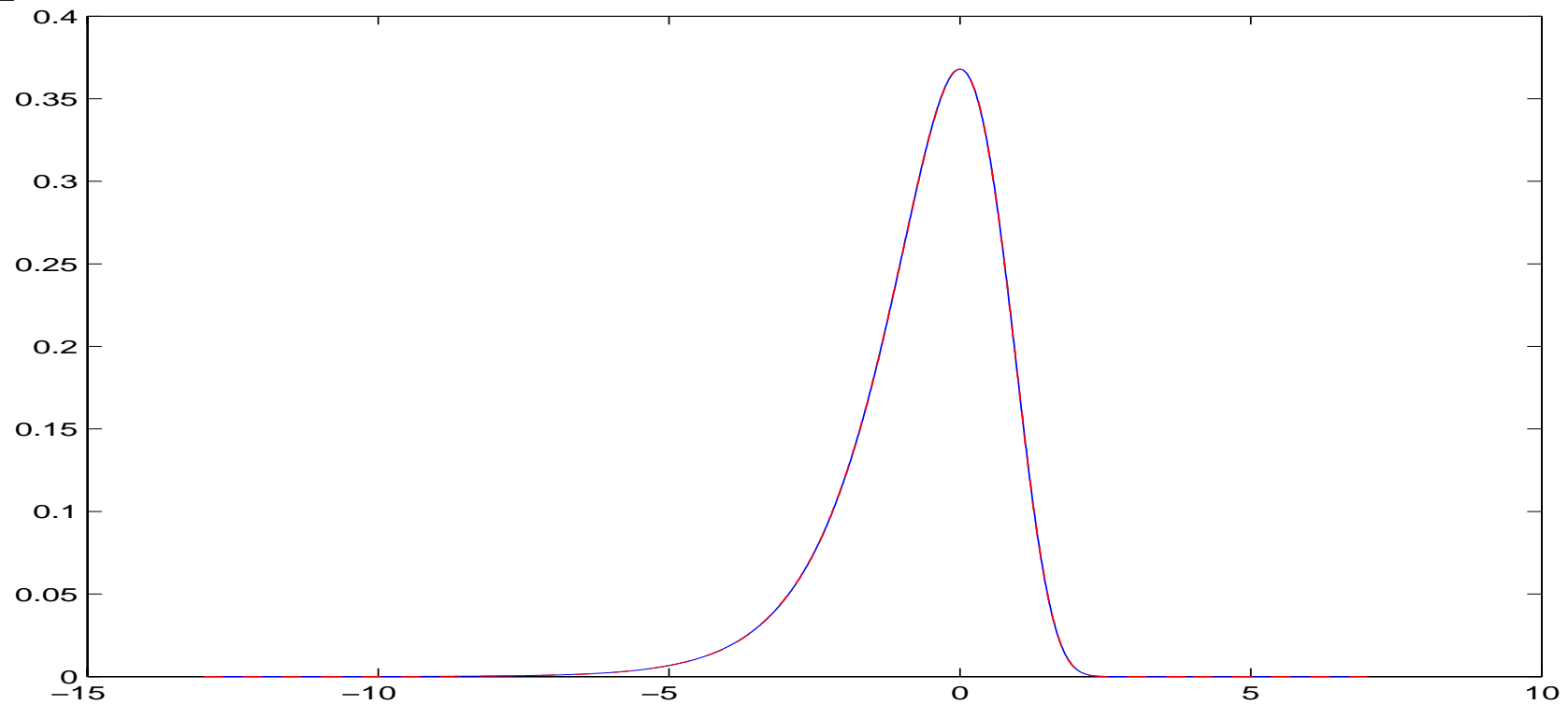


Figure 1: Comparing the density of the $-\log(\mathcal{E}(1))$ -distribution (type I extreme value distribution) with a normal mixture approximation with 10 components

Data Augmentation - Step II

Frühwirth-Schnatter and Waldl (2004) - major revision with a modified list of authors coming out soon

- Introduce for each ε_i the latent component indicator r_i as missing data.
- Estimate the latent utilities y_i^u and the latent component indicator r_i jointly β using a two step MCMC algorithm

Auxiliary mixture sampling

Auxiliary Mixture Sampling

Estimate the latent utilities y_i^u and the latent component indicator r_i jointly β using a two step MCMC algorithm

1. Sample β conditional on (y_1^u, \dots, y_N^u) and indicator (r_1, \dots, r_N) from the normal, linear regression model

$$y_i^u = \mathbf{x}_i \beta + m_{r_i} + \varepsilon_i, \quad \varepsilon_i \sim \mathcal{N}(0, s_{r_i}^2).$$

2. **NEW**: Recover the latent utilities y_i^u and the latent indicators r_i conditional on knowing β

Auxiliary Mixture Sampling - Step 2

- Sample the latent utility y_i^u conditional on β and y as explained above (need two uniform random number and $\lambda_i = \exp(\mathbf{x}_i\beta)$)
- Sample r_i conditional on knowing y_i^u from the following discrete density, where $(w_j, m_j, s_j^2), j = 1, \dots, 10$ are the parameters of the finite mixture approximation:

$$\Pr(r_i = j | y_i^u, \beta) \propto \frac{w_j}{s_j} \exp\left(-\frac{(y_i^u - \log \lambda_i - m_j)^2}{2s_j^2}\right).$$

Related Work

Related algorithm with different kind of data augmentation:
Holmes and Held (2006)

Related work using mixtures approximation:

- Stochastic volatility modelling: Kim, Shephard, and Chib (1998) and Chib, Nardari, and Shephard (2002) use a 7 component normal mixture approximation of the density of a $\log \chi^2$ -distribution
- Spectral analysis: Carter and Kohn (1997) use a 5 component normal mixture approximation of the density of a $\log(\mathcal{E}(1))$ -distribution

Multinomial data

- Data with $m + 1$ categories, labelled $\{0, 1, \dots, m\}$
- There is a latent utility $y_{ki}^u, k = 0, \dots, m$ for each category. $y_{ki}^u, k \geq 1$ is modelled as being dependent on covariates:

$$y_{ki}^u = \mathbf{x}_i \boldsymbol{\beta}_k + \varepsilon_{ki}.$$

- The observed category is the category with maximal utility
- The multinomial model is the marginal distribution of y_i , if y_{0i}^u and $\varepsilon_{ki}, k = 1, \dots, m$, follow a type I extreme value distribution (McFadden 1974).

Auxiliary Mixture Sampling for Multinomial Data

1. Draw the parameters β_1, \dots, β_m from the normal posterior density of following standard regression model:

$$y_{ki}^u = \mathbf{x}_i \beta_k + m_{r_{ki}} + \varepsilon_{ki}, \quad \varepsilon_{ki} \sim \mathcal{N}(0, s_{r_{ki}}^2).$$

2. **NEW**: Recover the utility y_{ki}^u and the indicator r_{ki} for each $i = 1, \dots, N$ and for each $k = 1, \dots, m$ using $\log \lambda_{ki} = \mathbf{x}_i \beta_k$

Holmes and Held (2006) - sample $\beta_k | \beta_{-k}$

Regression Models for Count Data

$$y_i | \boldsymbol{\beta} \sim \mathcal{P}(\exp(\mathbf{x}_i \boldsymbol{\beta})) = \mathcal{P}(\lambda_i)$$

y_i . . . observed counts

\mathbf{x}_i . . . covariates

$\boldsymbol{\beta}$. . . regression coefficient

Auxiliary Mixture Sampling for Count Data

Frühwirth-Schnatter and Wagner (2004)

- Instead of the utilities use the inter-arrival times of a hidden Poisson process with mean λ_i
- Mixture approximation of the density of a type I extreme value distributed random variable: Introduction of the component indicator of this mixture as a second sequence of missing data

Excursion: The Poisson Process

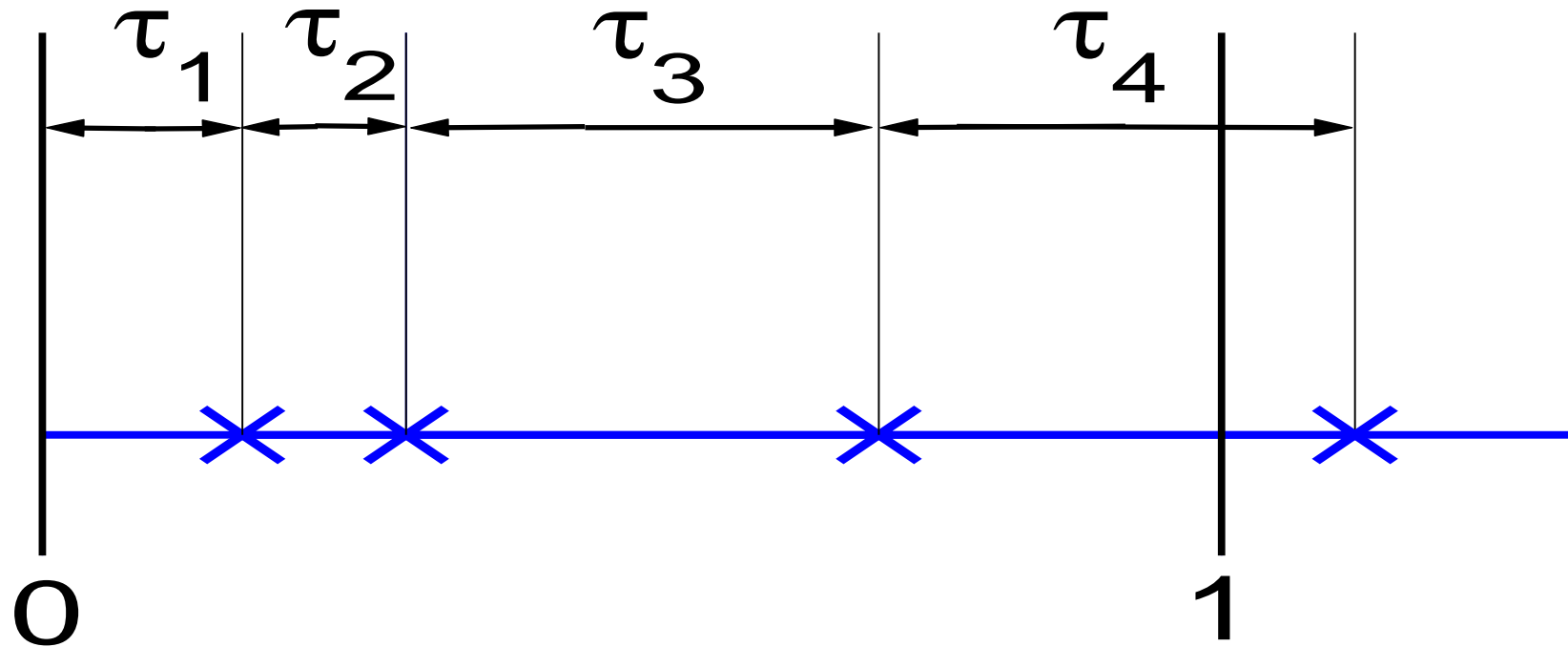


Figure 2: Poisson process: crosses mark the occurrence of an event

Achieving Linearity - Data Augmentation Step 1

- For each $i = 1, \dots, N$ introduce the hidden inter-arrival times τ_{ij} , $j = 1, \dots, (y_i + 1)$, of the unobserved Poisson process as missing data
- The inter-arrival times τ_{ij} are $\mathcal{E}(\lambda_t)$ distributed, therefore:

$$-\log \tau_{ij} = \mathbf{x}_i \boldsymbol{\beta} + \varepsilon_{ij}, \quad j = 1, \dots, (y_i + 1)$$

$p(\varepsilon_{ij})$ type I extreme value distribution

Achieving Normality - Data Augmentation Step 2

- Same as for binary and multinomial data
- Approximation of the density of ε_{ij} by a normal mixture of 10 components \Rightarrow indicator r_{ij} for each $i = 1, \dots, N$ and for each $j = 1, \dots, (y_i + 1)$

Auxiliary Mixture Sampling for Count Data

1. Sample β conditional on all τ_{ij} and r_{ij} from the normal posterior of following standard regression model:

$$-\log \tau_{ij} = \mathbf{x}_i \beta + m_{r_{ij}} + \varepsilon_{ij}, \quad \varepsilon_i \sim \mathcal{N}\left(0, s_{r_{ij}}^2\right).$$

2. **NEW**: Recover the inter arrival times τ_{ij} and the indicator r_{ij} for each $i = 1, \dots, N$ and for each $j = 1, \dots, (y_i + 1)$ using $\log \lambda_{ij} = \mathbf{x}_i \beta$

More Complex Models

Auxiliary mixture sampling only based on knowing $\lambda_i = \exp(\mathbf{x}_i\boldsymbol{\beta}) \Rightarrow$ easily extended to more general models:

- State-space models Frühwirth-Schnatter and Wagner (2004)
- Random-effect models (Frühwirth-Schnatter and Waldl (2004), Tüchler (2003))
- Markov switching autoregressive models for binary time series and times series of counts (Stefan, 2005)
- Space-time models (Gschlössl and Czado, 2005)

Application to Model Choice and Variable Selection

- Model choice for state space models for discrete-valued data
- Variable selection for regression models for discrete-valued data
- Covariance selection in random-effect models for discrete-valued data

Time Series of Road Accidents of Pedestrians

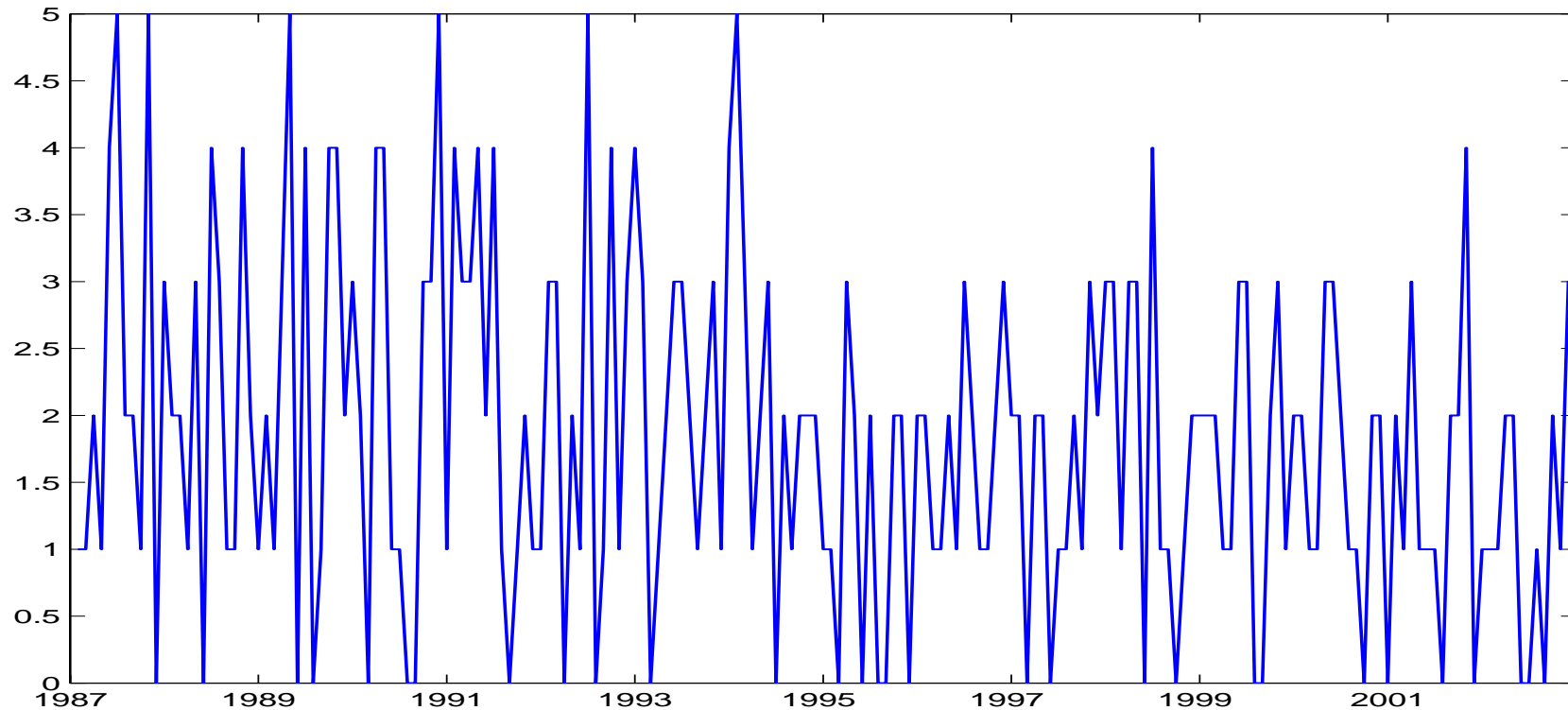


Figure 3: Killed or seriously children (aged 6-10) in Linz (Austria), 1987:01 - 2002:12

Time Series of Road Accidents of Pedestrians

A legal intervention intended to increase road safety took place during the observation period. More precisely, an amendment increasing priority for pedestrians became effective on **October 1, 1994**. Since then pedestrians who want to use a crosswalk have to be granted crossing.

⇒ Study intervention effect

Basic structural model for Poisson counts

The intensity λ_t has a trend and a seasonal component.

$$y_t \sim \mathcal{P}(e^{\mu_t} e^{s_t})$$

$$y_t \sim \mathcal{P}(\lambda_t), \quad \log(\lambda_t) = \mu_t + s_t$$

Basic structural model for Poisson counts

- Trend component

$$\mu_t = \mu_{t-1} + a_{t-1} + w_{1t}, \quad w_{1t} \sim \mathcal{N}(0, \theta_1)$$

$$a_t = a_{t-1} + w_{2t}, \quad w_{2t} \sim \mathcal{N}(0, \theta_2)$$

- Intervention effect: Modification of trend component for $t = t_{int}$:

$$\mu_t = \mu_{t-1} + a_{t-1} + \delta + w_{1t}$$

- seasonal component

$$s_t = -s_{t-1} - \dots - s_{t-11} + w_{3t}, \quad w_{3t} \sim \mathcal{N}(0, \theta_4^2)$$

Dynamic Generalized Linear Model

Special case of following state space form for Poisson counts:

$$y_t | \lambda_t \sim \mathcal{P}(\lambda_t)$$

$$\lambda_t = \exp(Z_t^1 \alpha + Z_t^2 \beta_t)$$

$$\beta_t = F_t \beta_{t-1} + w_t \quad w_t \sim \mathcal{N}(0, Q)$$

Joint prior distribution $p(\beta^T)$ of the state vector $\beta^T = (\beta_0, \dots, \beta_T)$ and $p(\alpha)$ are normal; $p(Q)$ is an inverted Wishart or the product of inverted Gammas

Auxiliary Mixture Sampling for DGLM

- Multi-move sampling of the **whole sequence** β_0, \dots, β_T and α by forward filtering-backward sampling from $p(\alpha, \beta^T | y, Q, S, \tau)$ as in (Frühwirth-Schnatter 1994), (Carter and Kohn 1994) and (De Jong and Shephard 1995): recursive sampling from multivariate normals with rank(Q)
- sample Q from $p(Q | y, \beta^T, R, \tau)$ (inverted Wishart distribution).
- **NEW**: Joint sampling of R, τ from $p(R, \tau | y, \beta^T, Q)$

Auxiliary Mixture Sampling for Road Safety Data

- Auxiliary mixture sampling was run 12000 times with a burn-in of 2000 runs.
- Priors: $\mu_0 \sim \mathcal{N}(0, 1)$, $a_0 \sim \mathcal{N}(0, 1)$, $s_j \sim \mathcal{N}(0, 1)$, $j = 1, \dots, 12$.

Time Series of Road Accidents of Children

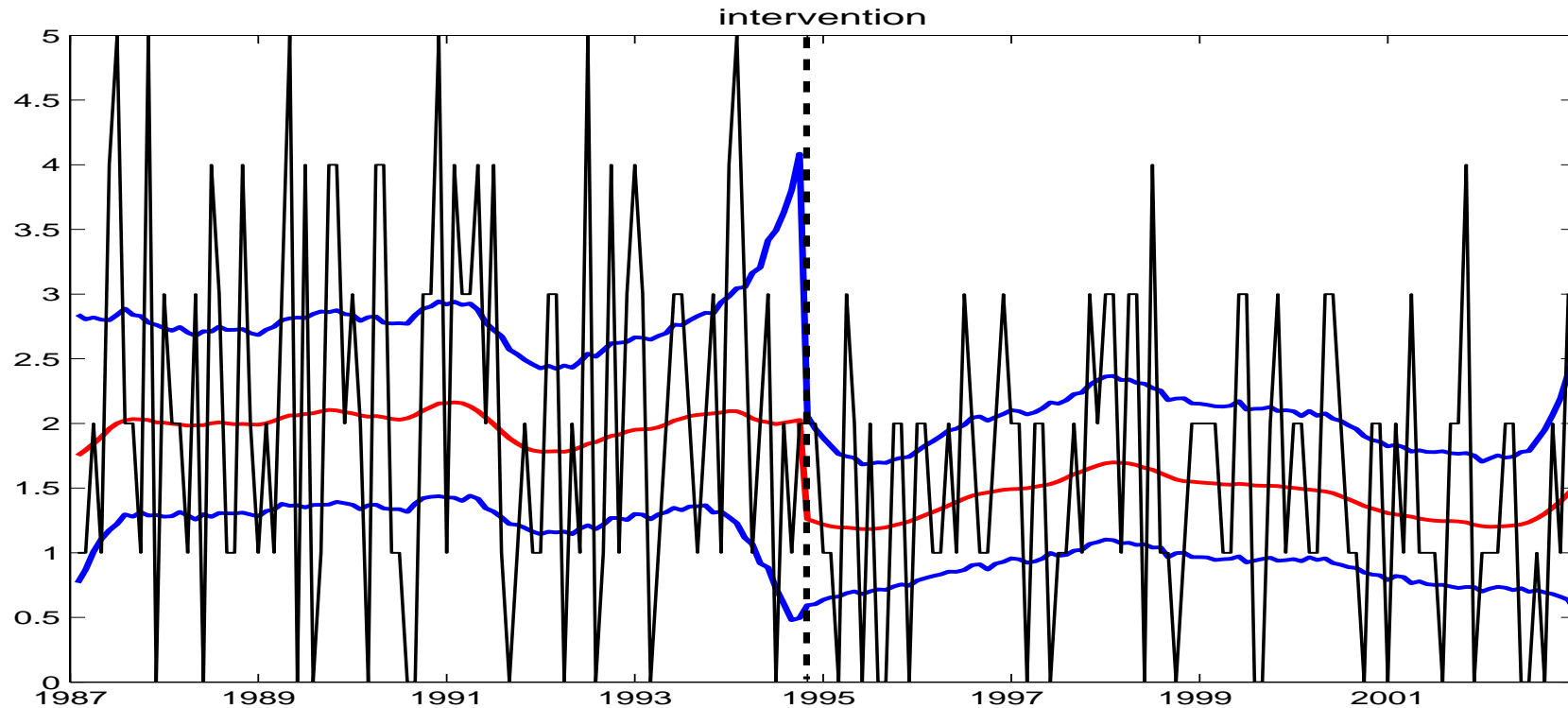


Figure 4: Counts and estimated trend component $\exp(\mu_t)$

Time Series of Road Accidents of Children

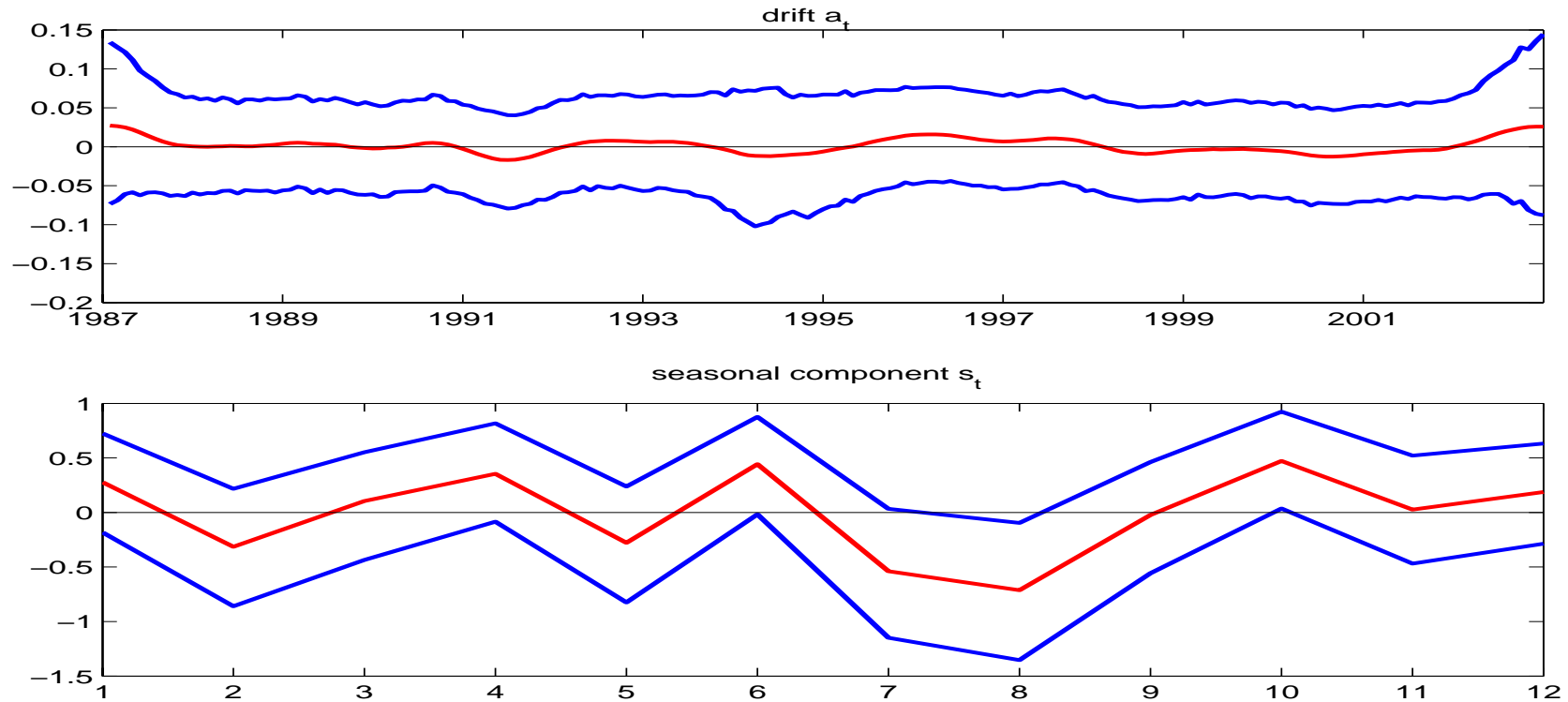


Figure 5: Trend and seasonal component

Time Series of Road Accidents of Children

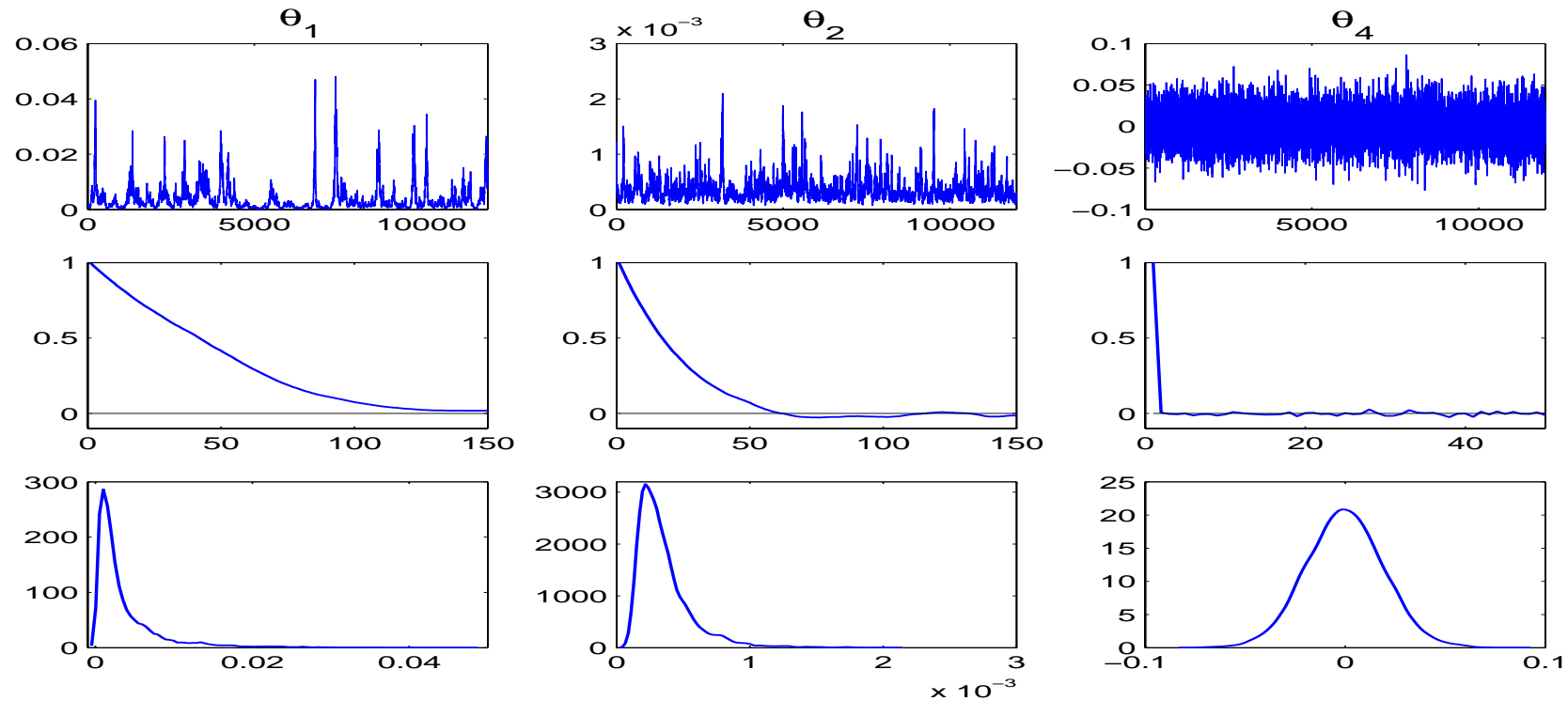


Figure 6: Auxiliary Gibbs sampling results for the variances

Model Choice for Using Marginal Likelihoods

Estimation of marginal likelihoods for state space models of discrete-valued data by the method of Chib (1995) is feasible from the output of the auxiliary mixture sampler:

$$p(y) = \frac{p(y | (\beta_0, \beta_1, \dots, \beta_T, \alpha)^*) p((\beta_0, \beta_1, \dots, \beta_T, \alpha)^*)}{p((\beta_0, \beta_1, \dots, \beta_T, \alpha)^* | y)}$$

Model Choice for Using Marginal Likelihoods

$p((\beta_0, \beta_1, \dots, \beta_T, \alpha)^* | y)$ is computed from the output of the auxiliary mixture sampler as following mixture of normal distributions

$$\begin{aligned} & p((\beta_0, \beta_1, \dots, \beta_T, \alpha)^* | y) \\ &= \frac{1}{M} \sum_{m=1}^M p((\beta_0, \beta_1, \dots, \beta_T, \alpha)^* | \boldsymbol{\tau}^{(m)}, R^{(m)}, \boldsymbol{\vartheta}^{(m)}, y) \end{aligned}$$

Similar formula for binary and multinomial data

Application to Road Safety Data

Table 1: Marginal Likelihoods

local level model - fixed season, no intervention	-242.6029
local level model - fixed season, intervention	-191.5628
dynamic trends model - fixed season, no intervention	-271.8189
dynamic trends model - fixed season, intervention	-258.9480
basic structural model, intervention	–
basic structural model, no intervention	–
fixed effects - full seasonal, intervention	-329.3423
fixed effects - full seasonal, no intervention	-331.5685
fixed effects - holiday effect, intervention	-308.9187

Variable selection for discrete-valued regression models

y_i . . . dependent for subject i , $i = 1, \dots, N$

Z_i . . . design matrix / covariates ($1 \times d$)

β . . . regression parameter

Regression model for discrete-valued data

$$\Pr(y_i = 1 | \beta) = \frac{\exp(Z_i \beta)}{1 + \exp(Z_i \beta)},$$

$$y_i \sim \mathcal{P}(\exp(Z_i \beta))$$

Extension to multinomial regression models possible

Variable selection for discrete-valued regression models

Variable Selection for the elements of β as for the standard linear regression model, see e.g. George and McCulloch (1997)

We define indicators δ_j for each element β_j of β , $j = 1, \dots, d$:

$$\beta_j = 0, \quad \text{iff } \delta_j = 0,$$

$$\beta_j \neq 0, \quad \text{iff } \delta_j = 1.$$

Related work by Holmes and Held (2006) for the binary and the multinomial regression model

Variable selection through auxiliary mixture sampling

Introducing the auxiliary variables \mathbf{R} (indicators in the mixture) and $\boldsymbol{\tau}$ (\mathbf{y}^u) leads to a conditionally Gaussian model

1. Sampling of the indicators $\boldsymbol{\delta}$ recursively from $p(\delta_j | \boldsymbol{\delta}_{-j}, \mathbf{R}, \boldsymbol{\tau}, \mathbf{y})$, $j = 1, \dots, d$;
2. Sampling of the non-zero regression parameters $\boldsymbol{\beta}^\delta$ from the normal posterior distribution $p(\boldsymbol{\beta}^\delta | \boldsymbol{\delta}, \mathbf{R}, \boldsymbol{\tau}, \mathbf{y})$
3. **NEW**: Joint sampling of $(\mathbf{R}, \boldsymbol{\tau})$ from $p(\mathbf{R}, \boldsymbol{\tau} | \mathbf{y}, \boldsymbol{\beta})$ using $\log \lambda_i = \mathbf{Z}_i \boldsymbol{\beta}$, $i = 1, \dots, N$

Example - Credit-scoring data

Fahrmeir, Hamerle, Tutz (1996)

- 1000 consumer credits:
 $y_{it} = 1$ for 700 creditworthy,
 $y_{it} = 0$ for 300 not creditworthy
- 20 risk factors are observed; e.g. duration of credit, amount of credit, intended use, marital status, age, ...

We select risk factors and estimate the effect of these risk factors.

Example - Credit-scoring data

- We use dummy coding for the categorical variables and have 36 elements in θ .
- We start with the most general model, which includes all effects.
- We carry out 50.000 iterations of the auxiliary mixture sampler and leave 10.000 for burn-in.

Example - Credit-scoring data

Posterior probability of the indicators to be non-zero ($M = 40000$):

$$\hat{P}(\delta_j = 1|y) = \frac{1}{S} \sum_{m=1}^M \delta_j^{(m)},$$

12 effects with posterior probability greater than 0.5.

Example - Credit-scoring data

risk-factor	$\hat{P}(\delta = 1 y) = 1$	$\hat{\theta}$
no running account	0.9	-0.54
good running account	1	1.3
duration	0.99	-0.04
credit-worthy in the past	0.99	0.96
private purpose	0.96	0.53
higher savings	0.98	0.81
same employer		
≤ 1 year	0.44	-0.24
$1 < .. \leq 4$ years	0.22	-0.02
> 4 years	0.67	0.33

Example - Credit-scoring data

risk-factor	$\hat{P}(\delta = 1 y) = 1$	$\hat{\theta}$
rate (% of income)		
$20 \leq .. < 35$	0.17	-0.00
< 20	0.83	-0.44
male, not single	0.52	0.21
female, single	0.12	0.02
other debtors	0.19	-0.09
surety	0.67	0.66
same home		
$1 < .. \leq 7$ years	0.43	-0.18
$.. > 7$ years	0.16	-0.02

Example - Credit-scoring data

risk-factor	$\hat{P}(\delta = 1 y) = 1$	$\hat{\theta}$
no foreign worker	0.82	1.28
car owner	0.14	-0.02
life insurance	0.11	-0.01
real estate	0.26	-0.12
age	0.37	0.00
other credits		
bank	0.11	-0.03
others	0.67	0.33
rented flat	0.23	-0.08
freehold flat	0.15	0.04

Example - Credit-scoring data

risk-factor	$\hat{P}(\delta = 1 y) = 1$	$\hat{\theta}$
no. of credits in the past		
1, 3	0.11	0.01
≥ 4	0.13	0.05
unskilled, resident	0.1	-0.00
skilled	0.11	-0.01
manager/self-employed	0.1	-0.00
> 3 persons entitled to maintenance	0.12	0.01
telephone	0.24	0.06
intercept		-0.29

Covariance Selection for Random Effect Models

Chen and Dunson (2003), Frühwirth-Schnatter and Tüchler (2004): Covariance selection for random effect models for normally distributed data

- Decompose the covariance matrix of the random effects using the Cholesky decomposition
- Use the non-centered parameterization \rightarrow the Cholesky factors are regression coefficients in a regression model
- Use variable selection on the elements of the Cholesky factors

Binary logit random effects model

Binary data $y_{it} \in \{0, 1\}$, $i = 1, \dots, N$ subjects, $t = 1, \dots, T_i$ repetitions

$$Pr(y_{it} = 1 | \beta_i) = \frac{\exp(x_{it}\beta_i)}{1 + \exp(x_{it}\beta_i)},$$
$$\beta_i \sim N_{d_r}(\beta^G, \mathbf{Q}).$$

Covariance Selection

Tüchler (2003): extension to discrete-valued data is possible using the auxiliary mixture sampler

- Cholesky decomposition: $Q = C \cdot C'$ (C lower triangular)
- $\beta_i = \beta^G + C \cdot \tilde{z}_i$ with $\tilde{z}_i \sim N_{d_r}(0, I)$.

$$Pr(y_{it} = 1 | \beta^G, C, \tilde{z}_i) = \frac{\exp(x_{it}\beta^G + x_{it}C\tilde{z}_i)}{1 + \exp(x_{it}\beta^G + x_{it}C\tilde{z}_i)}$$

—→ Variable selection for the elements of C .

Covariance Selection

Define indicators γ_{lm} for the lower triangular elements C :

$$\begin{aligned} C_{lm} &= 0, & \text{iff } \gamma_{lm} &= 0, \\ C_{lm} &\neq 0, & \text{iff } \gamma_{lm} &= 1, \\ & & \text{for } l &\geq m \end{aligned}$$

→ Estimate the non-zero elements C^γ from the reduced model:

$$\Pr(y_{it} = 1 | \beta^G, C, \gamma, \tilde{z}_i) = \frac{\exp(x_{it}\beta^G + x_{it}^\gamma C^\gamma \tilde{z}_i)}{1 + \exp(x_{it}\beta^G + x_{it}^\gamma C^\gamma \tilde{z}_i)}.$$

Covariance selection through auxiliary mixture sampling

1. Sampling of the indicators γ recursively from $p(\gamma_{lm} | \gamma_{-lm}, \mathbf{R}, \boldsymbol{\tau}, \mathbf{y}, z^N)$;
2. Sampling of the regression parameter $\boldsymbol{\beta}^G$ and the Cholesky factor C^γ from the normal posterior distribution $p(\boldsymbol{\beta}^G, C^\gamma | \gamma, \mathbf{R}, \boldsymbol{\tau}, z^N, \mathbf{y})$
3. Sampling of the random effects $\tilde{z}^N = \{\tilde{z}_i\}$ from $p(z^N | \boldsymbol{\beta}^G, \mathbf{R}, \boldsymbol{\tau}, \mathbf{y})$;
4. **NEW:** Joint sampling of $(\mathbf{R}, \boldsymbol{\tau})$ from $p(\mathbf{R}, \boldsymbol{\tau} | \mathbf{y}, \boldsymbol{\beta})$ using $\log \lambda_{it} = x_{it}\beta_i$, $i = 1, \dots, N$, $t = 1, \dots, T_i$

Travel Data - Marketing Application

- Conjoint study about packaged city trips (Hatzinger and Mazanez, 2005)
- 499 consumers were asked to rate 9 different city trip packages (1 ... high, 0 ... low)

Attributes:

destination: close to Vienna or medium distance
transport mode: bus ; train; plane
duration of stay: 2 days; 3 days; 4 days
price in Euro: 258; 372 ; 482

Auxiliary Mixture Sampling and Covariance Selection

- Fractional prior for β^G and C^γ ;
- $M = 40000$ iterations (after 10000 iterations burn-in).

Travel Data - estimates of β^G

baseline: close to Vienna, bus, 2 days, 258 Euro

baseline	-1.8
medium distance to Vienna	0.8
transport mode - train	1.1
transport mode - plane	3.0
duration of stay - 3 days	0.7
duration of stay - 4 days	0.8
price in Euro 372	-0.6
price in Euro 482	-2.2

Travel Data - estimates of indicators for Q

1	0.95	1	1	0.83	0.56	0.43	0.39
0.95	1	1	0.99	0.86	0.89	0.61	0.63
1	1	1	1	0.9	0.92	0.74	0.89
1	0.99	1	1	0.91	0.9	0.77	0.88
0.83	0.86	0.9	0.91	1	1	1	1
0.56	0.89	0.92	0.9	1	1	1	1
0.43	0.61	0.74	0.77	1	1	1	1
0.39	0.63	0.89	0.88	1	1	1	1

Summary

- Computational device for model selection and variable selection for discrete-valued data
- Data augmentation using auxiliary variables lead to a conditionally Gaussian models
- No free lunch: there is a small approximation error when using the auxiliary mixture sampler

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